



#### 4. Parameters

**n**

Input: The actual state dimension,  $n$ , i.e., the order of the matrix  $A$ .

Constraint:  $\mathbf{n} \geq 1$ .

**p**

Input: The actual output dimension,  $p$ .

Constraint:  $\mathbf{p} \geq 1$ .

**reduceto**

Input: Indicates whether the matrix pair  $(A,C)$  is to be reduced to upper or lower observer Hessenberg form as follows:

**reduceto** = **Nag\_UH\_Observer**, (Upper observer Hessenberg form);

**reduceto** = **Nag\_LH\_Observer**, (Lower observer Hessenberg form).

**a[n][tda]**

Input: The leading  $n$  by  $n$  part of this array must contain the state transition matrix  $A$  to be transformed.

Output: The leading  $n$  by  $n$  part of this array contains the transformed state transition matrix  $UAU^T$ .

**tda**

Input: The trailing dimension of array **a** as declared in the calling program.

Constraint:  $\mathbf{tda} \geq \mathbf{n}$ .

**c[p][tdc]**

Input: The leading  $p$  by  $n$  part of this array must contain the output matrix  $C$  to be transformed.

Output: The leading  $p$  by  $n$  part of this array contains the transformed output matrix  $CU^T$ .

**tdc**

The trailing dimension of array **c** as declared in the calling program.

Constraint:  $\mathbf{tdc} \geq \mathbf{n}$ .

**u[n][tdu]**

Input: If **u** is defined, then the leading  $n$  by  $n$  part of this array must contain either a transformation matrix (e.g. from a previous call to this function) or be initialised as the identity matrix. If this information is not to be input then **u** must be set to the null pointer, i.e., (double \*)0.

Output: If **u** is defined, then the leading  $n$  by  $n$  part of this array contains the product of the input matrix  $U$  and the state-space transformation matrix which reduces the given pair to observer Hessenberg form.

**tdu**

Input: The trailing dimension of array **u** as declared in the calling program.

Constraint:  $\mathbf{tdu} \geq \mathbf{n}$  if **u** is defined.

**fail**

The NAG error parameter, see the Essential Introduction to the NAG C Library.

## 5. Error Indications and Warnings

### NE\_BAD\_PARAM

On entry parameter **reduceto** had an illegal value.

### NE\_INT\_ARG\_LT

On entry, **n** must not be less than 1: **n** = *<value>*.

On entry, **p** must not be less than 1: **p** = *<value>*.

### NE\_2\_INT\_ARG\_LT

On entry **tda** = *<value>* while **n** = *<value>*.

These parameters must satisfy **tda**  $\geq$  **n**.

On entry **tdc** = *<value>* while **n** = *<value>*.

These parameters must satisfy **tdc**  $\geq$  **n**.

On entry **tdu** = *<value>* while **n** = *<value>*.

These parameters must satisfy **tdu**  $\geq$  **n**.

## 6. Further Comments

The algorithm requires  $O((n+m)n^2)$  operations (see Van Dooren and Verhaegen 1985).

### 6.1. Accuracy

The algorithm is backward stable.

### 6.2. References

Van Dooren P and Verhaegen M (1985) On the use of unitary state-space transformations. *In: Contemporary Mathematics on Linear Algebra and its Role in Systems Theory* **47** AMS, Providence.

## 7. See Also

nag\_kalman\_sqrt\_filt\_info\_invar (g13edc)

## 8. Example

To reduce the matrix pair  $(A,C)$  to upper observer Hessenberg form.

### 8.1. Program Text

```
/* nag_trans_hessenberg_observer(g13ewc) Example Program
 *
 * Copyright 1994 Numerical Algorithms Group
 *
 * Mark 3, 1994.
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nagg13.h>

#define NMAX 20
#define PMAX 20
```

```

#define TDA NMAX
#define TDC NMAX
#define TDU NMAX

main()
{
    double a[NMAX][TDA];
    double c[PMAX][TDC];
    double u[NMAX][TDU];
    Integer i, j, n, p;
    Nag_ObserverForm reduceto;
    double zero = 0.0, one = 1.0;
    Integer nmax, pmax;

    Vprintf("g13ewc Example Program Results\n");

    /* Skip the heading in the data file and read the data. */
    Vscanf("%*[^\\n]");

    nmax = NMAX;
    pmax = PMAX;

    Vscanf("%ld%ld",&n,&p);
    if (n<=0 || p<=0 ||
        n>nmax || p>pmax)
    {
        Vfprintf(stderr,"One of n or p is out of range n = %ld, p = %ld\n", n, p);
        exit(EXIT_FAILURE);
    }

    reduceto = Nag_UH_Observer;

    for (j = 0; j < n; ++j)
        for (i = 0; i < n; ++i)
            Vscanf("%lf", &a[i][j]);
    for (i = 0; i < p; ++i)
        for (j = 0; j < n; ++j)
            Vscanf("%lf", &c[i][j]);

    if (u) /* Initialise U as the identity matrix. */
        for (i = 0; i < n; ++i)
        {
            for (j = 0; j < n; ++j)
                u[i][j] = zero;
            u[i][i] = one;
        }

    /* Reduce the pair (A,C) to reduceto observer Hessenberg form. */
    g13ewc(n, p, reduceto, (double *)a, (Integer)TDA, (double *)c, (Integer)TDC,
           (double *)u, (Integer)TDU, NAGERR_DEFAULT);

    Vprintf("\nThe transformed state transition matrix is \n\n");
    for (i = 0; i < n; ++i)
    {
        for (j = 0; j < n; ++j)
            Vprintf("%8.4f ",a[i][j]);
        Vprintf("\n");
    }
    Vprintf("\nThe transformed input matrix is \n\n");
    for (i = 0; i < p; ++i)
    {
        for (j = 0; j < n; ++j)
            Vprintf("%8.4f ",c[i][j]);
        Vprintf("\n");
    }
    if (u)
    {
        Vprintf("\nThe transformation matrix that reduces (A,C) \
to observer Hessenberg form is \n\n");
        for (i = 0; i < n; ++i)

```

```

        {
            for (j = 0; j < n; ++j)
                Vprintf("%8.4f ",u[i][j]);
            Vprintf("\n");
        }
    }
    exit(EXIT_SUCCESS);
}

```

## 8.2. Program Data

g13ewc Example Program Data

```

5      3
15.0  21.0  -3.0   3.0   9.0
20.0   1.0   2.0   8.0   9.0
 4.0   1.0   7.0  13.0  14.0
 5.0   6.0  12.0  13.0  -6.0
 5.0  11.0  17.0  -7.0  -1.0
 7.0  -1.0   3.0  -6.0  -3.0
 4.0   5.0   6.0  -2.0  -3.0
 9.0   8.0   5.0   2.0   1.0

```

## 8.3. Program Results

g13ewc Example Program Results

The transformed state transition matrix is

```

 7.1637  -0.9691 -16.5046  0.2869  0.9205
-2.3285  11.5431  -8.7471  3.4122  -3.7118
-10.5440 -7.6032  -0.3215  3.6571  -0.4335
-3.6845   5.6449   0.5906 -15.6996  17.4267
 0.0000  -6.4260   1.5591  14.4317  32.3143

```

The transformed input matrix is

```

 0.0000  0.0000  7.6585  5.2973  -4.1576
 0.0000  0.0000  0.0000  5.8305  -7.4837
 0.0000  0.0000  0.0000  0.0000 -13.2288

```

The transformation matrix that reduces (A,C) to observer Hessenberg form is

```

 0.1863  -0.4823  0.2645  0.6648  -0.4698
-0.1137  -0.3601  0.6748  -0.0512  0.6320
 0.6742  -0.5151  -0.1897  -0.4940  -0.0097
-0.1872  0.0813  0.5439  -0.5371  -0.6116
-0.6803  -0.6047  -0.3780  -0.1512  -0.0756

```

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